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| **2014.7.14 (Monday) Room N420** |
| Lecture 1 (9:00~11:00)Introduction and modeling | Lecture 2 (15:00-17:00)Modeling and analysis |
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| Lecture 8 (9:00~11:00) Optimal control |  |
| **2014.7.23 (Wednesday ) Room N420** |
| Lecture 9 (9:00~11:00) Optimal control to a manifold |  |

Hu Xiaoming received the B.S. degree from the University of Science and Technology of China in 1983, and the M.S. and Ph.D. degrees from the Arizona State University in 1986 and 1989 respectively. He served as a research assistant at the Institute of Automation, the Chinese Academy of Sciences, from 1983 to 1984. From 1989 to 1990 he was a Gustafsson Postdoctoral Fellow at the Royal Institute of Technology, Stockholm, where he is currently a professor of Optimization and Systems Theory. His main research interests are in nonlinear control systems, nonlinear observer design, sensing and active perception, motion planning, control of multi-agent systems, and mobile manipulation.

注：参加此课程的博士生在课程结束后完成相关试卷，可作为博士生课程。